Numerical analysis of the performance of a venturi-shaped roof for natural ventilation: influence of building width

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Abstract
A numerical analysis with Computational Fluid Dynamics (CFD) is performed to investigate the influence of building width on the performance of a venturi-shaped roof (called Ventec roof) for natural ventilation. The specific roof configuration is intended to create a negative pressure in the narrowest roof section (contraction) which can be used to partly or completely drive the natural ventilation of the building zones. In previous studies, the influence of the roof configuration on its performance was analysed in detail, however these studies were all performed for a fixed building geometry, i.e. a tower building with floor plan 20 x 20 m² and a height of 50 m. It is important to analyse the performance of the Ventec roof for different building widths. Therefore, the present paper presents CFD simulations for building (and roof) widths of 20, 40, 80, 120 and 160 m. The 3D steady Reynolds-averaged Navier-Stokes (RANS) approach with the Renormalization Group (RNG) k-ε model is used. The simulations are based on grid-sensitivity analysis and on validation by comparison with wind tunnel experiments. The simulations show that the aerodynamic performance of the roof in terms of the negative pressure in the contraction improves with 31% when the building width is increased from 20 m to 40 m, while further increasing the building width only provides relatively small additional improvements. The increased performance with increasing building width is attributed to the larger overpressure upstream of the building and to the larger negative pressure and larger size (height) of the wake behind the building.

Keywords: Computational Fluid Dynamics (CFD); building dimensions; natural ventilation; venturi-effect; buildings; airflow

1. Introduction
Natural ventilation or hybrid natural-mechanical ventilation of buildings can be used to provide a comfortable and healthy indoor environment with reduced energy consumption. Natural ventilation is based on either wind-induced pressure differences or thermally-induced pressure differences, or – most often – a combination of both (Linden 1999, Hunt and Linden 1999, Li and Delsante 2001, Larsen and Heiselberg 2008, Chen 2009, van Hooff and Blocken 2010, Bronsema 2010). The potential for natural ventilation can be significantly enhanced by the design of the building. Because the roof of a building is often the most exposed part to the oncoming wind, in particular the roof geometry can be employed to enhance natural ventilation. This reasoning has driven the design of a specific venturi-shaped roof by Bronsema in the framework of the research project “Earth, Wind & Fire – Air-conditioning powered by Nature” (Bronsema 2010) (Fig. 1). This roof is called the Ventec roof. It consists of a disk-shaped roof construction that is positioned at a certain height above the actual building, creating a contraction that is expected to provide significant negative pressures due to the so-called Venturi-effect. The negative pressure can be used to partly or completely drive the natural ventilation of the building zones. For this purpose, a vertical channel (not shown in Fig. 1) is provided in the centre of the building, which connects point E of the roof contraction with the building zones at each floor.

In a previous paper (van Hooff et al. 2011), the present authors provided a first analysis of the aerodynamic performance of this roof design by CFD and wind tunnel experiments. At this stage, it was found that adding vertical guiding vanes in the roof contraction actually did not improve but cancelled the effect of the contraction. Additional research (Blocken et al. 2011) indicated that due to the guiding vanes, the flow resistance through the

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contraction became too large and that therefore the oncoming wind would flow over and around the roof and the building, rather than being forced to flow between and along the guiding vanes in the contraction. This phenomenon was called the “wind-blocking effect” in earlier studies (Blocken et al. 2007a, 2008a, 2008b). To further optimize the roof performance, the venturi-effect and the wind-blocking effect were analysed in detail as a function of the roof contraction height and the contraction ratio (Blocken et al. 2011). However, these studies were all performed for a fixed building geometry, i.e. a tower building with floor plan 20 x 20 m² and a height of 50 m. It is not clear how the building geometry influences the performance of the roof, therefore it is important to analyse the performance of the Ventec roof for different building widths.

In the present study, 3D steady Reynolds-averaged Navier-Stokes (RANS) CFD with the Renormalization Group (RNG) $k-\varepsilon$ model is used to investigate the influence of the building width on the performance of the roof, in terms of the negative pressure in the contraction. Simulations are performed for building widths of 20, 40, 80, 120 and 160 m. Also the width of the roof is adjusted, to match the building width. Section 2 describes the building and roof geometry. Section 3 presents the CFD analysis for the basic configuration, including the grid-sensitivity analysis and the validation with the wind tunnel experiments. In section 4, the influence of the building width on the roof performance is analysed. Finally, sections 5 (discussion) and 6 (conclusions) conclude the paper.

2. Description of building and roof geometry

Figure 1 illustrates the basic geometry of the building with the venturi-shaped roof. The building has a rectangular (20 x 20 m²) floor plan and a height of 50 m, measured up to the edge of the roof. The Ventec roof consists of two parts. The lower part is constructed from half a “square disk” with dimensions 23.4 m x 23.4 m x 2 m (L x W x H) and it is positioned directly on top of the building, this way creating a roof overhang of 1.7 m on each side of the building, at which ventilation inlets will be placed. At a distance ‘c’ (contraction height) above this part of the roof a “full square disk” is positioned with dimensions 23.4 m x 23.4 m x 4 m (L x W x H), resulting in a nozzle-shaped roof entrance from all four sides of the building. This part can be supported by a set of slender vertical columns. In the present study, the inlet height $b = 6$ m and the contraction height $c = 2$ m. The additional building and roof configurations are generated by applying a geometrical scaling factor to the building and roof width. The scaling factors are 2, 4, 6 and 8, yielding building widths $W = 40$ m, 80 m, 120 m and 160 m, respectively.

The position of interest inside the roof contraction is the point in the bottom centre of the roof, indicated with the letter E (from “exhaust”) in Figure 1a and b. In this study, the exhaust is considered to be closed and the surface pressure at this position will be evaluated. All simulations are conducted for an isolated building, i.e. without surrounding buildings. Therefore, all differences in wind speed and surface pressures between the different geometries are only due to changes in the width of the building and the roof.

3. Analysis of roof performance for the basic geometry

3.1. Wind tunnel measurements

Wind tunnel measurements were performed to validate the CFD simulations. A reduced-scale model (1:100) of the basic geometry (building width $W = 20$ m) was tested in the closed-circuit atmospheric boundary layer (ABL) wind tunnel at Peutz BV in Mook, the Netherlands. The dimensions of the wind tunnel test section are 3.2 x 1.8 m² (width x height), resulting in a blockage ratio of about 2%. The surface pressure was measured at position E (Fig. 1) with a HCLA12X5EB amplified differential pressure sensor from Sensortechnics. The wind speed in the roof contraction was measured in the centre of the contraction, at mid-height, using a NTC resistor element. The NTCs are operated with a constant current and are calibrated by Peutz by determining the relationship between wind speed and temperature (and corresponding resistance) of each individual probe. The probes are not direction-sensitive and due to the relatively long reaction time of the probes, only average wind speeds can be measured, with an accuracy of ±10%. Approach-flow vertical profiles of mean wind speed $U$ and turbulence intensity $I_u$ are measured at the edge of the turntable using hot-wire anemometers and are presented in Figure 2. The measured wind speed profile can be described by a logarithmic law with a friction velocity $u^* = 0.956$ m/s and an aerodynamic roughness length $y_0 = 0.005$ m (full scale: $y_0 = 0.5$ m). The incident reference wind speed at roof height (full scale: 50 m) is 10.5 m/s. Measurements are made for four wind directions: $\phi = 0^\circ$, $15^\circ$, $30^\circ$ and $45^\circ$, taking into account the symmetry of the building and the venturi-shaped roof.

3.2. Computational geometry and grid

The computational domain has (full-scale) dimensions $L \times B \times H = 1020$ m x 1020 m x 300 m (Fig. 3a). This domain shape allows modelling different wind directions ($0^\circ$ to $45^\circ$). A high-resolution computational grid was
constructed based on a grid-sensitivity analysis (see Fig. 3b and Fig. 4). The grid-sensitivity analysis is reported in (van Hooff et al. 2011) and (Blocken et al. 2011). The grid has at least 10 cells between each two adjacent surfaces as requested by the best practice guidelines by Franke et al. (2007) and Tominaga et al. (2008). The grid was generated using the grid generation technique presented by van Hooff and Blocken (2010), by which the geometry and the grid are created simultaneously by a series of extrusion operations. Note that the grids do not contain any pyramidal or tetrahedral cells. A high grid resolution is applied in the proximity of the roof in view of the expected large flow gradients (Fig. 4). The grid has a total of 2,375,016 cells.

3.3. Boundary conditions

At the inlet of the domain the measured approach-flow mean wind speed profile is imposed. Turbulent kinetic energy \( k \) is calculated from the turbulence intensity \( I_u \) using \( k = 0.5 (I_u U)^2 \). The turbulence dissipation rate \( \varepsilon \) is given by \( \varepsilon = \frac{(u*)^3}{\kappa (y+y_0)} \), where \( y \) is the height coordinate, \( \kappa \) the von Karman constant (\( \kappa = 0.42 \)) and \( u* \) the friction velocity related to the logarithmic mean wind speed profile. At the ground and building surfaces, the standard wall functions by Launder and Spalding (1974) are used with the sand-grain based roughness modification by Cebeci and Bradshaw (1977). For the ground surface, the parameters \( k_S \) and \( C_S \), to be used in Fluent (Fluent Inc. 2006) should be selected to represent the rough fetch upstream of the building model. Therefore, \( k_S \) and \( C_S \) have to be determined using their appropriate consistency relationship with \( y_0 \). This relationship was derived by Blocken et al. (2007b) for Fluent and CFX. For Fluent 6, up to at least version 6.3, it is given by \( k_S = 9.793 y_0 / C_S \). The combination \( k_S = 0.98 \) m and \( C_S = 5 \) is selected. The building surfaces are assumed to be smooth (\( k_S = 0 \) m and \( C_S = 0.5 \)). Zero static pressure is imposed at the outlet of the domain and the top of the domain is modelled as a slip wall (zero normal velocity and zero normal gradients of all variables).

3.4. Solver settings

The 3D steady RANS equations are solved in combination with the RNG \( k-\varepsilon \) turbulence model (Yakhot et al. 1992) using Fluent 6.3.26. The RNG \( k-\varepsilon \) turbulence model was chosen because of its good performance in predicting the surface pressures on the windward building facades and in the roof opening in the previous study (van Hooff et al. 2011) and because of its superior performance in an earlier study by Evola and Popov (2006). Pressure-velocity coupling is taken care of by the SIMPLE algorithm, pressure interpolation is standard and second-order discretization schemes are used for both the convection terms and the viscous terms of the governing equations. Convergence has been monitored carefully and the iterations have been terminated when all scaled residuals showed no further reduction with increasing number of iterations. At this stage, the scaled residuals (Fluent Inc. 2006) were: \( 10^{-4} \) for continuity, \( 10^{-7} \) for momentum, \( 10^{-6} \) for turbulent kinetic energy and \( 10^{-4} \) for turbulence dissipation rate.

3.5. Results and validation

Figure 5 compares the results from the wind tunnel measurements and the results from the CFD simulations. Figure 5a shows the pressure coefficients \( C_p \) at point E, which are defined as \( C_p = (P-P_0)/(0.5 \rho U_{ref}^2) \), where \( P \) is the local static pressure, \( P_0 \) the reference static pressure, \( \rho \) the air density and \( U_{ref} \) the approach-flow wind speed at building height (\( = 50 \) m). Fig. 5b provides a similar comparison for the dimensionless velocity magnitude \( (U/U_{ref}) \) at mid-height in the centre of the roof contraction. Note that in this ratio, \( U \) is the magnitude of the 3D velocity vector. In general a good agreement is obtained, where the CFD results are within 10%-15% of the measurements. Based on this validation study, the influence of building width is investigated in the next section.

4. Analysis of roof performance for different building widths

4.1. Computational settings and parameters

The geometry and the grid for the different building widths are obtained by applying a linear scaling factor along the width of the building. The resulting geometries are shown in Fig. 6. The resulting computational grids are illustrated in Fig. 7. The boundary conditions and solver settings are identical to those outlined in the previous section. However, simulations are only performed for one wind direction, i.e. perpendicular to the wide facade of the building.

4.2. Results

Fig. 8a displays the pressure coefficient \( C_p \) at point E as a function of the building width \( W \). When \( W \) increases from 20 m to 40 m, the \( C_p \) value improves (i.e. decreases) with about 31% to a value of -1.24. Further increasing
W leads to additional, but smaller improvements, down to $C_p = -1.38$ for $W = 160$ m. Fig. 8b shows the corresponding dimensionless velocity magnitude ($U/U_{ref}$) at mid-height in the centre of the roof contraction. Fig. 9 displays the same parameter $U/U_{ref}$ in the vertical centreplane through the building. As $W$ increases, so does the area of low wind speed (stagnation zone) upstream of the building. In addition, also the size (height) of the wake behind the building increases. These observations and their effect on the flow through the roof are more clearly shown in Fig. 10. It appears that the increase of the stagnation zone in front of the building and the increase of the size of the wake and the underpressure value in the wake are responsible for the increase in absolute pressure at point E and therefore for the improved performance of the roof with increasing building width.

Figs. 11a-d show the ratio $U/U_{ref}$ and the static pressure $P$ along a horizontal line through the roof contraction, as shown in Fig. 11e. In Figs. 11a-d, the dashed vertical lines mark the positions of the edges of the roof. Clearly shows that the increasing building width $W$ leads to a decrease of the wind speed and to an increase of the overpressure upstream of the roof. The increasing building width $W$ also leads to a decrease (more negative value) of the underpressure directly downstream of the roof (see Fig. 11d). As a result, the flow through the roof is enhanced and the absolute value of the underpressure is increased.

5. Discussion

The evaluation of the aerodynamic performance of the roof has been mainly conducted based on the value of the negative pressure coefficient at point E. However, the simulations showed that large pressure gradients are present in the roof contraction. Point E was chosen because of its position in the centre of the contraction, and because it corresponded to the location of the point measurement in the wind tunnel model. A future study on the aerodynamic performance of the roof will include modelling the exhaust flow rate through the vertical channel, and that enters the roof contraction due to the generated negative pressure.

The present study only evaluated the influence of building width for wind direction perpendicular to the wide facade of the building. Further research will focus on oblique wind directions, and on the influence of building height and of the approach-flow wind conditions on the performance of the roof.

6. Summary and conclusions

This paper has presented a numerical analysis with CFD to investigate the influence of building width on the performance of a venturi-shaped roof for natural ventilation. In previous studies, the influence of the roof configuration on its performance was analysed in detail, however these studies were all performed for a fixed building geometry, i.e. a tower building with a floor plan of 20 x 20 m² and a height of 50 m. It was important to analyse the performance of the roof for different building widths. Therefore, the present paper has presented CFD simulations for building (and roof) widths of 20, 40, 80, 120 and 160 m. The 3D steady Reynolds-averaged Navier-Stokes (RANS) approach with the Renormalization Group (RNG) k-ε model were used. The simulations were based on grid-sensitivity analysis and on validation by comparison with wind tunnel experiments. The simulations showed that the aerodynamic performance of the roof in terms of the negative pressure in the contraction improved with about 31% when the building width is increased from 20 m to 40 m, while further increasing the building width only provided small additional improvements. The increased performance with increasing building width is attributed to the larger overpressure upstream of the building and to the larger negative pressure and larger size (height) of the wake behind the building.

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FIGURES

Figure 1: (a) Perspective view of the basic (20 x 20 m²) building geometry with venturi-shaped roof (Ventec roof) and main dimensions. (b) Vertical cross-section of the building and Ventec roof with indication of position E where the surface pressure is evaluated. In the present study: b = 6 m and c = 2 m.

Figure 2: (a) Measured approach-flow mean wind speed profile along a vertical line at the upstream edge of the turntable (full-scale dimensions; log law profile with $u^* = 0.956$ m/s and $y_0 = 0.5$ m). (b) Measured turbulence intensity T.I. along the same vertical line (full-scale dimensions).
Fig. 3: (a) View of the building in its computational domain (full-scale dimensions). (b) Perspective view of the computational grid at some of the domain surfaces. Total number of cells is 2,375,016.

Fig. 4: Perspective view of computational grid on the building and ground surfaces. Total number of cells is 2,375,016.

Fig. 5: Comparison of wind tunnel measurements and CFD simulation results for four wind directions ($\phi = 0^\circ$, $\phi = 15^\circ$, $\phi = 30^\circ$, $\phi = 45^\circ$). (a) Pressure coefficient $C_P$ at point E. (b) Dimensionless velocity magnitude $U/U_{ref}$ at mid-height in the centre of the roof contraction. $U_{ref}$ is the approach-flow wind speed at building height (50 m).
Fig. 6: Five different building and roof geometries: (a) $W = 20$ m; (b) $W = 40$ m; (c) $W = 80$ m; (d) $W = 120$ m; (e) $W = 160$ m. The configurations are tested for wind perpendicular to the wide facade.
Fig. 7: Computational grids used for the five different building and roof geometries. (a) W = 20 m; (b) W = 40 m; (c) W = 80 m; (d) W = 120 m; (e) W = 160 m. All grids consist of 2,375,016 cells.
Fig. 8: (a) Wind pressure coefficient $C_p$ at point E as a function of building width, for wind perpendicular to the wide facade. (b) Dimensionless velocity magnitude ($U/U_{ref}$) at mid-height in the centre of the roof contraction as a function of building width, for wind perpendicular to the wide facade. $U_{ref}$ is the approach-flow wind speed at building height (50 m).

Fig. 9: Contours of dimensionless velocity magnitude ($U/U_{ref}$) in the vertical centreplane through the building, for wind perpendicular to the wide facade. (a) $W = 20$ m; (b) $W = 40$ m; (c) $W = 80$ m; (d) $W = 120$ m; (e) $W = 160$ m. $U_{ref}$ is the approach-flow wind speed at building height (50 m).
Fig. 10: Enlarged view of contours of dimensionless velocity magnitude ($U/U_{\text{ref}}$) in the vertical centreplane through the building, for wind perpendicular to the wide facade. (a) $W = 20$ m; (b) $W = 40$ m; (c) $W = 80$ m; (d) $W = 120$ m; (e) $W = 160$ m. $U_{\text{ref}}$ is the approach-flow wind speed at building height (50 m).
Fig. 11: (a,c) Profiles of dimensionless velocity magnitude ($U/U_{ref}$) upstream and downstream of the building as a function of building width $W$, along the plotting line indicated in figure (e). (b,d) Static pressure profiles along the same line. The dashed vertical lines mark the positions of the edges of the roof. (e) Location of the plotting line in the vertical centreplane through the building.